Abstract Of The Disclosure

A method for determining the float angle of a motor vehicle is described, a yaw sensor determining the yaw rate of the motor vehicle. According to this method, the direction of the velocity in the center of gravity of the vehicle in particular is determined by a frequency analysis of the signals received by a GPS receiver located in the motor vehicle, and the float angle is determined as a function of at least the yaw rate and the direction of the velocity of the motor vehicle.